



# Secure Computation of Fingerprint Alignment and Matching

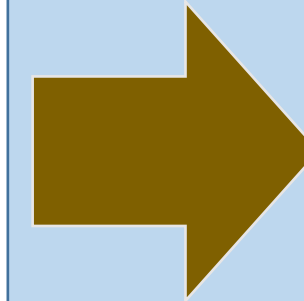


Fattaneh Bayatbabolghani, Marina Blanton

Department of Computer Science and Engineering, University of Notre Dame

## Motivation

- ❑ Fingerprint images are one of the most accurate type of biometry used biometric verification and identification.
- ❑ Fingerprint images are highly sensitive due to their ability to uniquely identify the data owner .

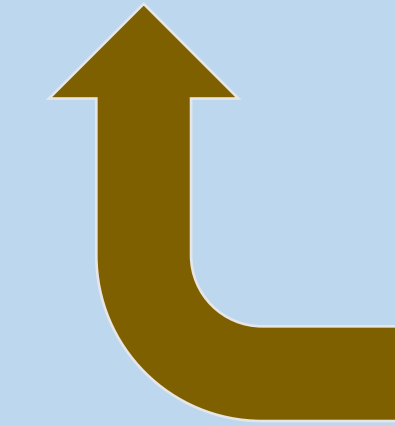


## Goals

- ❑ To build secure protocols for fingerprint **alignment** (first time) and matching based on the most precise or efficient algorithms in the biometric literature.
- ❑ To develop secure computation techniques based on garbled circuit evaluation and linear secret sharing.

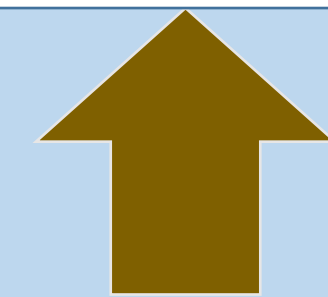
## Building Security Solutions

- ❑ Standard Building Blocks such as addition/subtraction, multiplication, comparison, and compaction.
- ❑ More complicated building blocks such as division, **square root** (new for secure two-party computation), **sine** (totally new), and **cosine** (totally new).



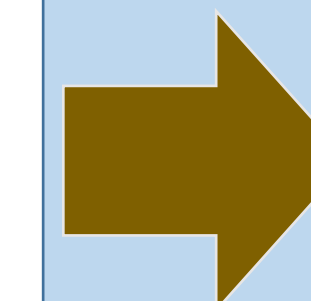
## Security Model

- 1- Secure two-party computation in presence of semi-honest or fully malicious participants.
- 2- Secure multi-party computation in presence of semi-honest or fully malicious participants.



## Problem Setup

- 1- Two entities would like to compare fingerprints they respectively possess, without revealing any information about their data to the other party.
- 2- One or more the data owners are computationally limited and would like to securely offload their work to more powerful servers or cloud providers

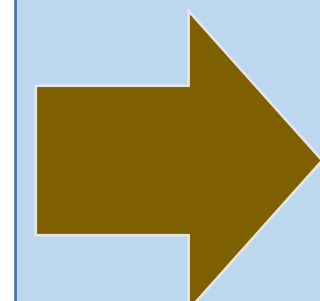


## Extracted Features



Extracted features are represented by the following elements:

- 1) an  $x$ -coordinate,
- 2) a  $y$ - coordinate,
- 3) orientation in radians denoted by  $\theta$ .



## Fingerprint Recognition

- ❑ *Fingerprint matching based on minutiae alignment: Consider all possible alignments between two fingerprint images  $S$  and  $T$  and select the alignment that maximizes the matching score.*  

$$\text{Matching score} = \frac{\# \text{matched minutia points}}{\# \text{minutia points } S \times \# \text{minutia points } T}$$
- ❑ *Fingerprint matching based on trimmed iterative closest point algorithm: Align two sets of 3-D points of helper data  $S$  and  $T$  based on trimmed iterative closest point (TICP) to find matching score.*
- ❑ *Fingerprint matching based on spectral minutiae representation: Modify the representation of minutia points by using Fourier transform and then reduce feature size to make recognition process faster without losing precision. At the end, consider different alignment and compute similarity score.*

This work was supported by grant CNS-1223699 from the National Science Foundation.